



Mobile platform steps with **ZARGES Ergo Stop -**



40255062

Mobile access or work platforms with easy-going steps. Ideal for work over long periods, even with tools and frequent changes of working position. Large-area platform with guardrail for safe and ergonomic working at heights.

Product description

- Different angles of inclination: 45° for comfortable access, 60° for confined spaces.
- Selection of tread widths 600 mm, 800 mm or 1000 mm.
- Serrated aluminium (R10) step and platform surfaces as standard. Steel gratings (R12) and perforated steel plates (R13) are also available for higher non-slip performance.
- Individually adjustable platform lengths.
- Platform steps instantly ready for use due to an innovative brake system.
- An antistatic version of the chassis is also available.
- ZARGES Ergo Stop all four castors can be braked conveniently using the foot pedal on the flight of steps.
- · Customised guardrail configuration on the platform, with optional swing door or pole barrier.
- Maximum flexibility with optional handrails and



More information about the product, accessories and spare parts: https://www.zarges.com/uk/products/mobile-platform-steps-with-zarges-ergo-stop-40255062



guardrails which can be removed without tools.

 Quick and simple assembly with the ZARGES connection system with a high level of preassembly.

Hints and special features

We recommend equipping the product in accordance with the German Equipment and Product Safety Act (ProdSG) with two-sided handrails and, for steps with platforms or maintenance platforms, all-round fall protection (e.g. guardrails). If handrails or guardrails are not desired, the operator must ensure sufficient regulatory protection.

Standard applied: DIN EN ISO 14 122.

Product features

Chassis width	Inclination	Load capacity	Max. load per tread	Number of treads
1420 mm	45 °	max. 300 kg	150 kg	12
Overall span	Platform length	Standards	Tread width	Vertical height
3447 mm	600 mm	NF EN ISO 14122-4	1000 mm	2790 mm
Warranty				
10 years				